

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	1	(calibrat\$3 with image with sensor) and ((geometric with travel with axis with bisector) same (total with (toe or toe-in) with angle) same (rear with axis) same vehicle)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 18:56
L2	1	(geometric with travel with axis with bisector) same (total with (toe or toe-in) with angle) same (rear with axis) same vehicle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 18:57
L4	1	(calibrat\$3 with image with sensor) and (geometric with travel with axis with bisector) and (total with (toe or toe-in) with angle) and (rear with axis) and vehicle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 18:59
L5	0	((alignment align\$3) with ((image with sensor) camera)) and (geometric with travel with axis) and (point\$3 with align\$3 with wheel) and vehicle and ((mak\$3 with point) same calibrat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 19:03
L6	0	((alignment align\$3) with ((image with sensor) camera)) and (geometric with travel with axis) and (point\$3 with align\$3 with wheel) and vehicle and ((mak\$3 with point) same calibrat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 19:04
L7	1	((alignment align\$3) with ((image with sensor) camera)) and (geometric with travel with axis) and (point\$3 with align\$3 with wheel) and vehicle and ((mark\$3 with point) same calibrat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 19:05
L8	0	((calibrat\$3 with datat) same (principal with point) same (principal with distance) same (distortion with parameter)) and (glass with pane) and (light with path)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 19:07
L10	1	((calibrat\$3 with data) same (principal with point) same (principal with distance) same (distortion with parameter)) and (glass with pane) and (light with path)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 19:07

S1	1	10/676155	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 18:52
S2	3	((image with sens\$3) same calibrat\$4 same (data parameter)) and (alignment same (image with sens\$3) same (geometric with axis) same vehicle)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/20 11:41
S3	3	((image with sens\$3) same calibrat\$4 same (data parameter)) and (alignment same (image with sens\$3)) and ((geometric with axis) same vehicle)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/20 13:50
S4	1	(((image with sens\$3) same calibrat\$4 same (data parameter)) and (alignment same (image with sens\$3))) and ((geometric with travel) same vehicle)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/20 12:24
S5	6	(((image with sens\$3) same calibrat\$4 same (data parameter)) and (alignment same (image with sens\$3))) and (geometric same vehicle)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/20 13:00
S6	59	"702"/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 13:38
S7	6	("702"/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter))) and (alignment same (image with sens\$3))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/22 09:47
S8	20	("702"/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter))) and (adjust\$6 same (image with sens\$3))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/20 13:49
S9	5	("702"/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter))) and (adjust\$6 same (image with sens\$3)) and geometric and vehicle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 19:11
S10	2	EP-1120746-\$ did.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 15:40

S11	4	"702"/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter)) and (adjust\$6 with image with sens\$3) and vehicle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 13:46
S12	10	(image with sens\$3) same calibrat\$4 same (data parameter) and (adjust\$6 with image with sens\$3) and vehicle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 14:39
S13	3	((image with sens\$3) same calibrat\$4 same (data parameter) and (adjust\$6 with image with sens\$3) and vehicle) and geometric\$6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 14:35
S14	1	((adjust\$6 align\$6) with image with sens\$3) same (geometric\$6 with travel with vehicle)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 14:41
S15	5	((adjust\$6 align\$6) with image with sens\$3) same (geometric\$6 with vehicle)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 15:40
S16	1	((adjust\$6 align\$6) with image with sens\$3) and (geometric\$6 with vehicle with (travel\$6 or mov\$6))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 18:26
S17	58	((adjust\$6 align\$6) with position with image with sens\$3) and (vehicle with (travel\$6 or mov\$6))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 15:51
S18	3	((adjust\$6 align\$6) with position with image with sens\$3) and (vehicle with (travel\$6 or mov\$6)) and ((evalu\$6 estimat\$6) with image with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 15:43
S19	15	((adjust\$6 align\$6) with position with ((image with sens\$3) or camera)) and (vehicle with (travel\$6 or mov\$6)) and ((evalu\$6 estimat\$6) with image with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 20:45
S20	2	(geometric\$6 adj travel\$6 adj axis) and vehicle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 18:27

S21	1	(((geometric\$6 with travel\$6 with axis) and vehicle) and (image near2 sensor)) and ((align\$6 or adjust\$6) with position with (image near2 sensor))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 19:00
S22	39	(((geometric\$6 with travel\$6 with axis) and vehicle) and (image near2 sensor)) and ((align\$6 or adjust\$6) with (image near2 sensor))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 18:31
S23	41	((geometric\$6 with travel\$6 with axis) and vehicle) and (image near2 sensor)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 18:32
S24	5	((adjust\$6 align\$6) with position with ((image with sens\$3) or camera)) and (vehicle with (travel\$6 or mov\$6)) and ((evalu\$6 estimat\$6) with image with data) and (angle with measur\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 18:35
S25	2	(((geometric\$6 near2 (travel\$6 driv\$3) near2 axis) and vehicle) and (image near2 sensor)) and ((align\$6 or adjust\$6) with position with (image near2 sensor))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 19:01
S26	3	(((geometric\$6 near2 (travel\$6 driv\$3) near2 axis) and vehicle) and (image near2 sensor)) and ((align\$6 or adjust\$6) with (image near2 sensor))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 19:01
S27	1	(intrinsic with calibration with data) and (camera with principal with point) and (camera with principal with distance) and (distortion with parameter) and (glass with pane)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 20:49
S28	1	(intrinsic with calibration with data) and (camera with principal with point) and (camera with principal with distance) and (glass with pane)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 20:48
S29	1	(intrinsic with calibration with data) and (camera with principal with point) and (camera with principal with distance)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 20:48

S30	1	(intrinsic with calibration with data) and (camera with point) and (camera with distance) and (distortion with parameter) and (glass with pane)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 20:50
S31	1	(intrinsic with calibration with data) and (camera with point) and (camera with distance) and (distortion with parameter) and glass	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/09/21 20:50
S32	11	("4152061" "4236794" "4789940" "4954962" "5036474" "5101277" "5170352" "5307170" "5400383" "5453845" "5460312").PN.	USPAT	OR	OFF	2004/09/22 09:42
S33	0	((("4152061" "4236794" "4789940" "4954962" "5036474" "5101277" "5170352" "5307170" "5400383" "5453845" "5460312").PN.) and (glass near2 pane)	USPAT	OR	ON	2004/09/22 09:47
S34	0	((("4152061" "4236794" "4789940" "4954962" "5036474" "5101277" "5170352" "5307170" "5400383" "5453845" "5460312").PN.) and (influence with glass)	USPAT	OR	ON	2004/09/22 09:48
S35	4	("4692806" "5134473" "5270756" "5296926").PN.	USPAT	OR	OFF	2004/09/22 09:44
S36	0	((("4692806" "5134473" "5270756" "5296926").PN.) and (glass near2 pane)	USPAT	OR	ON	2004/09/22 09:44
S37	0	((("4692806" "5134473" "5270756" "5296926").PN.) and (influence with glass)	USPAT	OR	ON	2004/09/22 09:44
S38	7	("5068791" "5247487" "5949685" "6047234" "6226571" "6275773" "6292752").PN.	USPAT	OR	OFF	2004/09/22 09:47
S39	0	((("5068791" "5247487" "5949685" "6047234" "6226571" "6275773" "6292752").PN.) and (glass near2 pane)	USPAT	OR	ON	2004/09/22 09:48

S40	0	(("5068791" "5247487" "5949685" "6047234" "6226571" "6275773" "6292752").PN.) and (influence with glass)	USPAT	OR	ON	2004/09/22 09:48
-----	---	--	-------	----	----	------------------